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## Short Pitch Smectic Structures in Electric Field

Barbara Rovšek  $^{a\ b}$  , Mojca Čepič  $^{a\ c}$  & Boštjan Žekš  $^{a}$   $^{d}$ 

<sup>a</sup> J. Stefan Institute, Jamova, Ljubljana, Slovenia

b Physics Department, University of Ljubljana, Ljubljana, Slovenia

<sup>c</sup> Faculty of Education, Kardeljeva plos<sup>\*</sup>čad, Ljubljana, Slovenia

<sup>d</sup> Institute of Biophysics, Medical Faculty, Lipičeva, Ljubljana, Slovenia

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#### Short Pitch Smectic Structures in Electric Field

#### Barbara Rovšek

J. Stefan Institute, Jamova, Ljubljana, Slovenia and Physics Department, University of Ljubljana, Ljubljana, Slovenia

### Mojca Čepič

J. Stefan Institute, Jamova, Ljubljana, Slovenia and Faculty of Education, Kardeljeva ploščad, Ljubljana, Slovenia

## Boštjan Žekš

J. Stefan Institute, Jamova, Ljubljana, Slovenia and Institute of Biophysics, Medical Faculty, Lipičeva, Ljubljana, Slovenia

When an external electric field is applied to short pitch polar smectics, their helical structures distort and unwind. The final transition to completely unwound structure can be continuous or discontinuous. Within the discrete phenomenological model the nature of the transition depends on the existence of the next-nearest neighboring layers interactions. If they are present, the transition is discontinuous. We try to elucidate this phenomenon.

Keywords: antiferroelectric liquid crystals; discrete model; electric field

#### INTRODUCTION

We consider the influence of the external electric field E on the helical structure of the polar short pitch smectic  $C_{\alpha}^*$  phase within the discrete phenomenological model [1]. Order parameter is a set of tilt vectors  $\xi_i$ , where  $\xi_i$  is a projection of the nematic director  $n_i$  in i-th layer onto the smectic plane. The part of the free energy which accounts for inter-layer interactions up to the next-nearest neighbors and interactions with external field is written in a

Address correspondence to Barbara Rovšek, Josef Stefan Institute, Jamova 39, Ljubljana, 1000 Slovenia. E-mail: barbara.rovsek@ijs.si

simple form:

$$G_{il} = \sum_{i} \left[ \frac{1}{4} a_{1} (\xi_{i-1} \cdot \xi_{i} + \xi_{i} \cdot \xi_{i+1}) + \frac{1}{4} f(\xi_{i-1} \times \xi_{i} + \xi_{i} \times \xi_{i+1}) + \frac{1}{16} a_{2} (\xi_{i-2} \cdot \xi_{i} + \xi_{i} \cdot \xi_{i+2}) - E \cdot P_{i} \right].$$

$$(1)$$

Indispensable terms in free energy take into account achiral  $(a_I)$  and chiral (f) nearest neighboring layers interactions and achiral next-nearest layers interactions  $(a_2)$ . External electric field E is parallel to the smectic layers and couples to a ferroelectric polarization of each smectic layer  $P_i = (\xi_i \times n_0)P_0D$ , where  $n_0$  is the smectic layer normal and D is the smectic layer thickness. Polarization  $P_i$  is parallel to the smectic layer and perpendicular to the tilt. Tilt vector can be described by the magnitude  $\theta_i$  and the phase angle of the tilt  $\phi_i$ . We do not consider variations of the magnitude of the tilt with electric field,  $\theta_i$  is taken to be the same in all the layers and constant,  $\theta_i = \theta_0$ . The magnitude of the polarization  $P_i$  is therefore also constant.

When the field is zero (E=0), minimization of the free energy (1) gives the zero-field short pitch helical structure of the smectic  $C_{\alpha}^*$  phase, if nearest and next-nearest layers interactions are competing. Reasonable choice for the model parameters is  $a_1>0$  and  $a_2<0$  [1]. Chiral interactions suppress degeneracy between two handedness. The pitch  $p_0$  of the helical structure of the smectic  $C_{\alpha}^*$  phase is defined by a relation between the model parameters

$$f = a_1 \tan \alpha_0 + a_2 \sin \alpha_0. \tag{2}$$

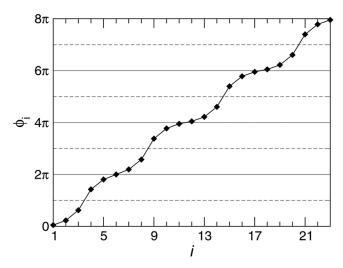
The angle  $\alpha_0$  describes the phase angle variations of the tilt from one layer to the next,  $\phi_{i+1} = \phi_i + \alpha_0$ . The pitch is related to  $\alpha_0$ ,  $p_0 = 2\pi D/\alpha_0$ . Since parameters  $a_1$ ,  $a_2$  and f can have in general any rational values, also the pitch  $p_0$  is in general incommensurate with the smectic layer thickness. It is relevant to say, that the same zero-field pitch can be obtained choosing different combinations of model parameters.

If the field is not zero minimization of the bulk free energy (1) leads to an infinite set of coupled equations

$$\begin{split} \frac{1}{2}a_{1}[-\sin(\phi_{i}-\phi_{i-1})+\sin(\phi_{i+1}-\phi_{i})] + \frac{1}{2}f[\cos(\phi_{i}-\phi_{i-1})\\ -\cos(\phi_{i+1}-\phi_{i})] + \frac{1}{8}a_{2}[-\sin(\phi_{i}-\phi_{i-2})\\ +\sin(\phi_{i+2}-\phi_{i})] + \frac{EP_{0}D}{\theta_{0}}\sin\phi_{i} = 0. \end{split} \tag{3}$$

We solved the system of Eqs. (3) numerically. First, the equations were linearized around the zero-field solution and then solved iteratively for larger and larger fields, the method is described elsewhere [2]. In the presence of electric field the helical structure distorts. The pitch increases with field and within one pitch the tilts reorient, so the average polarization is in direction of the field and also increases with field. In Figure 1 an example of the deformed structure is shown.

Here we concentrate on a particular result: we found, that the nature of the final transition to unwound structure at the critical field  $E_d$  depends on the value of parameter  $a_2$ , describing the next-nearest layers interactions. When the field is approaching the critical field for the complete unwinding (which is finite in all cases) the pitch extends over an integer number of smectic layers and further increases in steps of one layer [2]. If  $a_2 = 0$  the unwinding is found to be continuous, or better said, quasi-continuous: the pitch grows to infinity in steps of one layer. For  $a_2 \neq 0$  the final transition is discontinuous – from some finite final pitch of N layers  $(p(E_d) = ND, N)$  is



**FIGURE 1** Commensurate period of the structure with the pitch  $p(E)/p_0=1.15=23/4$  in electric field, whith  $p_0=5$  layers. Commensurate period consists of 23 smectic layers and is formed from three subperiods of six layers and one subperiod of five layers. Molecules tend to reorient so the polarization is parallel to the field as much as possible. Phase angle  $\phi_i$  is the angle between external field and polarization in i-th layer. All domain walls (where  $\phi_i=\pi,3\pi,5\pi,\ldots$ ) are alike and lengths of all subperiods within commensurate period differ at most for one layer.

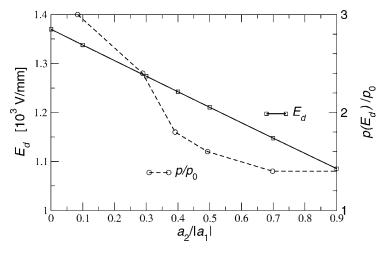
integer) to infinity. The larger  $a_2$ , the smaller the critical field  $E_d$  and shorter the final pitch  $p(E_d)$  before unwinding, as can be seen in Figure 2.

To explain the phenomenon, we go back to the bulk free energy describing the zero-field undistorted structure. When we insert the solution for the zero-field helical structure  $\theta_i = \theta_0$  and  $\phi_i = \phi_0 + i * \alpha$  back into the expression for the free energy, we obtain

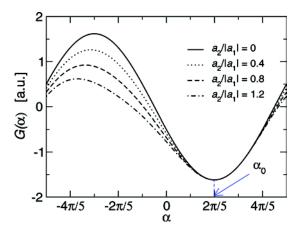
$$G(\alpha) = \theta_0^2 \sum_i \left[ \frac{1}{2} \alpha_1 \cos \alpha + \frac{1}{2} f \sin \alpha + \frac{1}{8} \alpha_2 \cos 2\alpha \right] \tag{4}$$

when E = 0. With only the nearest neighbours interactions (when  $a_2 = 0$ ) the free energy  $G(\alpha)$  is symmetric around the minimum as can be seen from a solid curve in Figure 3.

The minimum defines the equilibrium  $\alpha_0$ . Due to the symmetry around the minimum the energy costs for additional uniform twisting or unwinding of the helix for the same  $\Delta\alpha$ , where  $\alpha \to \alpha_0 \pm \Delta\alpha$ , are the



**FIGURE 2** Here it is shown, how the critical field  $E_d$  and the final pitch  $p(E_d)$  depend on the parameter  $a_2$ . We take few combinations of parameters  $a_2/|a_1|$  and  $f/|a_1|$  which all lead to the same zero-field pitch  $p_0=5$  layers and therefore the same zero-field structure. The structures however unwind differently when electric field is applied. If  $a_2=0$  (and  $f/|a_1|=-3.08$ ) the structure unwinds quasi-continuously. If  $a_2\neq 0$  (if  $a_2/|a_1|=0.3$ ,  $f/|a_1|=-2.79$  and so on, see Eq. (2)) the complete unwinding occurs at smaller critical field  $E_d$  and the pitch jumps from finite  $p(E_d)$  to infinity. Material parameters, that led to meaningful values of the critical electric field, were taken from [3]:  $P_0=100\,\mathrm{nC/cm^2},\ \theta_0=\pi/20$  and  $a_1/a=-1\,\mathrm{K}$  where  $a=4\times10^4\,\mathrm{J/m^3}.$ 



**FIGURE 3** Plot of the zero-field bulk free energy  $G(\alpha)$ , for  $p_0 = 5$  layers, which lead to  $\alpha_0 = 2\pi/5$ . Appropriate value of parameter  $f/|a_1|$  can be obtained from Eq. (2).

same. A balance between the elastic forces, stabilizing the helical structure, and electrostatic forces, stabilizing the unwound structure, is in the absence of next-nearest layers interactions obviously achieved in continuous distortion and unwinding of helical structure in electric field until it is unwound completely.

If  $a_2 \neq 0$ , the symmetry around the minimum is lost. In general, unwinding becomes energetically cheaper. This is apparent from dashed curves  $G(\alpha)$  for  $a_2 > 0$  in Figure 3, which are less steeper on the side towards  $\alpha = 0$ . It is more favorable to unwind then to twist, therefore the unwound regions grow faster with field, and the domain walls can also become wider. A consequence is a discontinuous jump to completely unwound planar structure at some critical field  $E_d$ . Being given the zero-field structure with certain pitch  $p_0$ , the critical field for a discontinuous transition to unwound structure is smaller for larger values of  $a_2$ , as can be observed from Figure 2.

To conclude: Whether the ultimate transition to unwound state at  $E_d$  occurs at certain finite or diverging pitch, crucially depends on the next-nearest neighbors interactions. If  $a_2$  is zero, the pitch diverges at  $E_d$ . If  $a_2 > 0$ , the pitch of deformed helix is finite at  $E_d$ , and a transition to unwound state is discontinuous. If electroclinic effect was not neglected, variations of magnitude of the tilt in electric field could mask the described behavior, which should be checked by more detailed analysis. Nevertheless we believe, that experimental observations of unwinding of the smectic  $C_{\alpha}^*$  short pitch structure in

electric field by means of several techniques [4,5] would lead to determination of the ratio  $f/a_2$ .

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